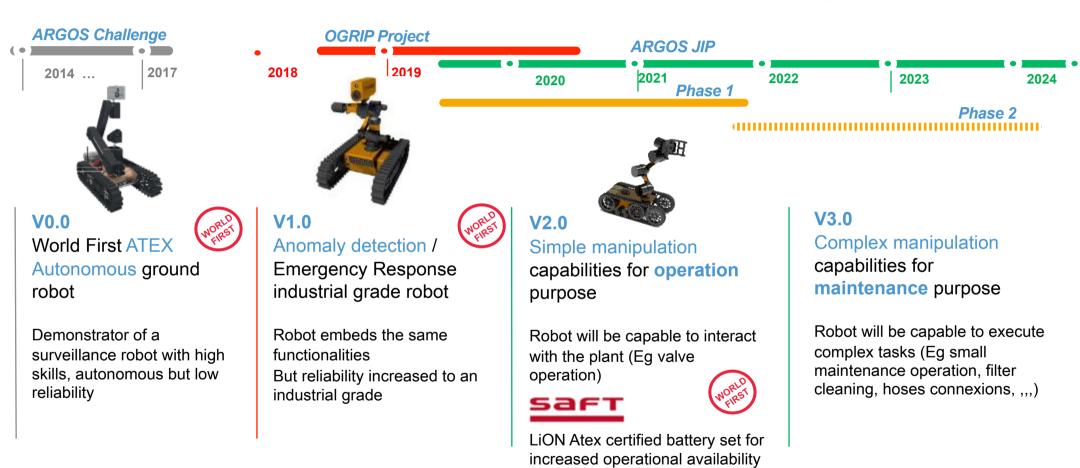


### **BOT DEVELOPMENT ROAD MAP**



onomous - ATEX - Water Resistant – Mobile - Multipurpose - Remotely Monitored – 24/7 Servi

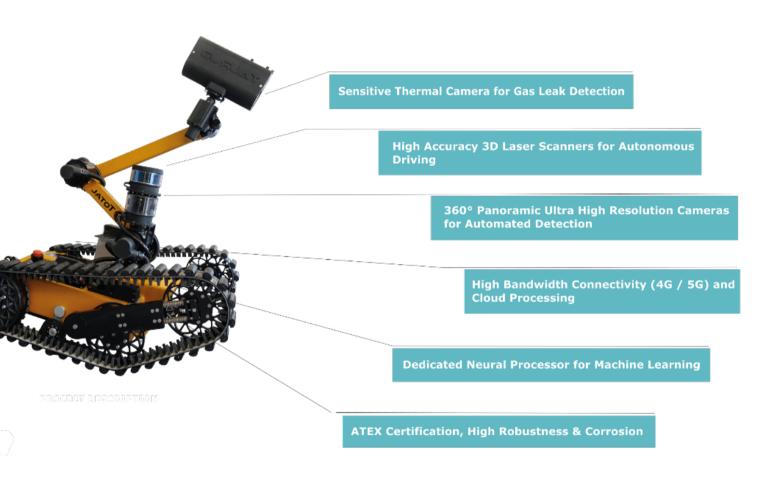


Design & qualify autonomous ground robots able to operate remote sites





# ANOMALY DETECTION ROBOT (V1.0 – OGRIP\*): GENERAL ARCHITECTURE



## **Anomaly detection**

- Audio (leaks, signature)
- Hot spots & fugitive emissions
- Gas detection
- Obstacles (+/-)

### **Process**

- Dial gauge reading
- Valve position

Mapping - Creation of 3D m

P: Offshore Ground Robot Industrial Pilot, commercial name The Taurob Inspector





# TESTS IN SHETLAND (UK): SITE DESCRIPTION

### Shetland Gas Plant

- Gas treatment for Laggan Tormorre subsea fields
- Condensate extraction, gas drying (MEG), compression (3 turbo compressors, LM2500)
- Start up in 2016

## Climatic conditions

- Windy and exposed to sea water (spindrifts)
- Good candidate to simulate offshore environment











## IMELINE OF SHETLAND GAS PLANT PILOT

### **OGRIP** project













t of OGRIP th 2018

te surveys & preparation ssions planning esign of new robot

### Sept, 2018

- · Ground testing
- Stair climbing
- 4G network
- Cloud connection
- Teleoperated

### May, 2019

- OGRIP prototype
- Autonomous missions
- Teleoperated stair climbing
- 3D model scan
- · Pictures to the cloud

### August, 2019

- Autonomous stair climbing
- · Autonomous missions
- Real time machine learning in the cloud

### Feb, 2020 Total Investors Day

 Live demos of autonomous missions in front of investors Oct, 2020 Start of Long duration operation - 1 year

- Hand over of robot to the plant
- 1 year in routine operation
- Day to day feedback
  - REX & learnings
  - Failures identification





# **TESTS ON K5 (OFFSHORE NETHERLANDS)**

### K5CC

- Gas production platforms with condensate recovery
- Located Offshore the Netherlands

## Tests performed:

- Conduct autonomous missions in condensate recovery area
- Conduct a Proof Of Concept for external corrosion and painting inspection
- Evaluate use cases on the platform





World First
Autonomous Robot on an offshore O&G platform





# ARGOS JIP PHASE 1 - SIMPLE MANIPULATION ROBOT EXECUTING ROUTINE PRODUCTION OPERATION TASKS



Operating valves designed as per API REC 6D (up to 150 Nm)
Pushing any buttons (e.g. ESDV reset)



Cleaning cameras, fire detectors

Moving Objects - Placing sensors (Eg: vibration)

Opening pig trap doors

Depressurization of well annulus

Chemical transfer from tote tank - Connecting Hoses

Exchanging Spare Parts











Typical use cases for wellhead platform or wellpad in NUF mode





# **ESTS IN TADI (LACQ, FRANCE)**

# Objectives

- Intensively run and test robots on a specifically created obstacle course site
- Test robot's adaptation to an EP environment (specs & new site ergonomic)
- Test integration of robotics in Total digital environment
- Test of new HMI for robot supervision by operators
- Map operating envelop deliver robots handbook

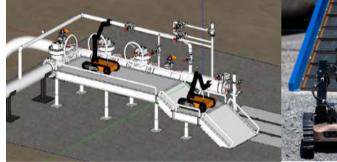
## **Opportunities**

- Trials & errors
- Training
- Be a showroom

## Examples of Tests

- Mobility and battery: stairs climbing optimisation, battery duration, new design for installations
- Operating envelop measurement
- Gas leak: emergency response support
- Operation reporting reliability



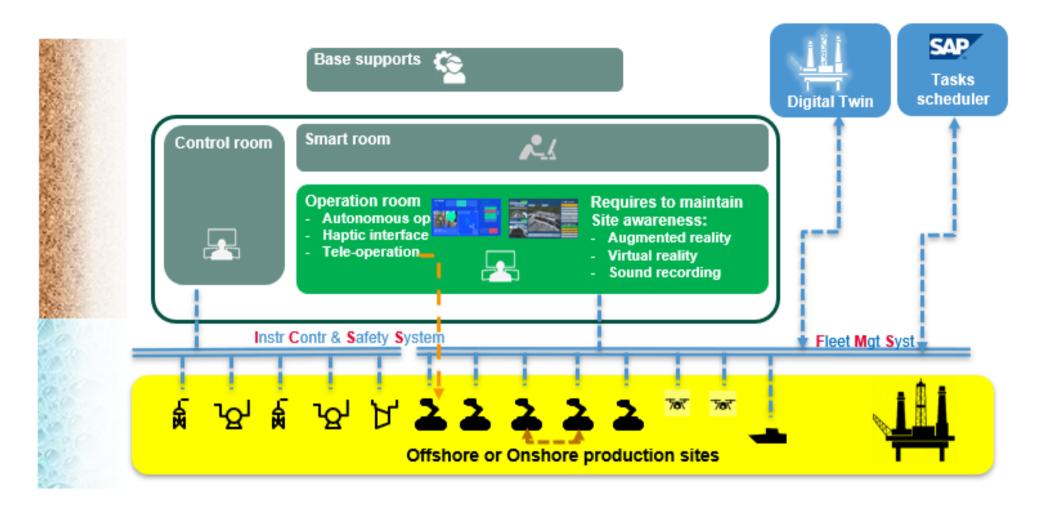








## REMOTE OPERATIONS FOR NUF - FLEET MANAGEMENT



Supervision Context:
Routine Operation / Anomaly Management / Emergency Response





## LOCATION OF DEPLOYMENT OF ROBOTS FOR TESTS ON TOTAL'S FACILITIES



- Lacq: 2014 ARGOS Challenge
- Shetlands: 2018 OGRIP
- Tempa Rossa: 2018 JIP technical preparation
- Lacq: 2019 Launch of Robotics Development platform
- Netherlands: 2020 First autonomous ATEX robot offshore in O&G



# **QUESTIONS?**





## BACK UP: FEW PUBLICATIONS & USEFUL LINKS

#### ADIPEC 2019: presence, publications & presentations

- ✓ SPE-197620-MS: Ground Robotics Enabler for Normally Unattended Installations
- ✓ SPE-197513-MS: Normally Unattended Installations, the New Frontier for Cost Reduction.
- Robot on Total stand with videos, live demos from Taurob lab in Vienna (our robotic partner)

**ARGOS brochure: Ground Robotics For Next-Generation Facilities 2014-2019** 

CNBC article and video "Getting ready for robot-operated oil rigs" in June 2019

https://www.cnbc.com/advertorial/2019/08/12/getting-ready-for-robot-operated-oil-rigs.html

Articles & Videos on Total site "Ground Robots: Technological Building Block for the Surveillance of Oil and Gas Sites"

2019: https://www.ep.total.com/en/innovations/research-development/ground-robots-key-future-architectures

2017: https://www.total.com/news/argonauts-robot-wins-argos-challenge

Video Meet OGRIP V1.0 Oct 2019: https://www.youtube.com/watch?v=E7svE6ITN-g

Video TOTAL ARGOS Challenge: Winning Team, July 2017: https://www.youtube.com/watch?v=-jPL-bSj0TY

The Press release made by our JIP sponsor OGTC and few articles that followed the release, Oct 2019

https://www.theogtc.com/newsroom/news/2019/industry-innovators-and-key-technology-developers-lead-the-way-with-robotics-development/

Oilfield Technology - https://www.offshore-technology.com/news/oatc-offshore-robot-development/

Rigzone - https://www.rigzone.com/news/offshore robot initiative wins pledges from operators-21-oct-2019-160112-article/

Offshore Magazine - https://www.offshore-mag.com/business-briefs/article/14068984/equinor-enters-offshore-robotics-consortium

### Launch of OGRIP project, April 2018

DIGIT: Article and Video, - https://digit.fyi/ogtc-robotics-trial/

Partner Web site

https://taurob.com/





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